

1 Introduction to Game Theoretic Modelling of Traffic Congestion

Example 1: This is the first example of game on graph. This game is played by 4000 drivers. In the graph, A is the source and B is the target. The labels on the edges of the graph represent the delays on the route. The driver can choose any path among the two.

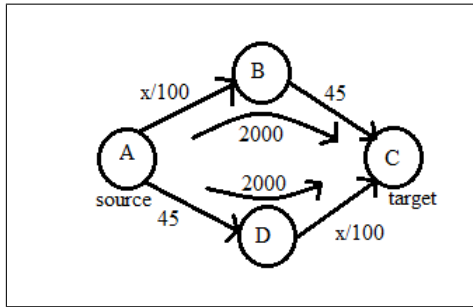


Figure 1: Diagram for the Example 1 showing the NE for the example in which 2000 drivers goes on both the paths

The travel time for each driver, when both routes have 2000 drivers will be: $20 + 45 = 65$ units of time.

Ques) Suppose we use the sum of travel time as the social welfare function than how good is the NE solution, relative to a choice that minimizes total travel time?

Suppose, p -drivers travel on path $A \rightarrow C \rightarrow B$
and the remaining $4000-p$ travels on $A \rightarrow D \rightarrow B$

$$\min_{0 \leq p \leq 4000} \left(\frac{p}{100} + 45 \right) p + (4000 - p) \left(\frac{4000 - p}{100} + 45 \right) \tag{1}$$

$$= \min_{0 \leq p \leq 4000} \frac{p^2}{100} + 45p + \frac{(4000 - p)^2}{100} + 4000 \times 45 \tag{2}$$

$$= \min_{0 \leq p \leq 4000} p^2 + (4000 - p)^2 \tag{3}$$

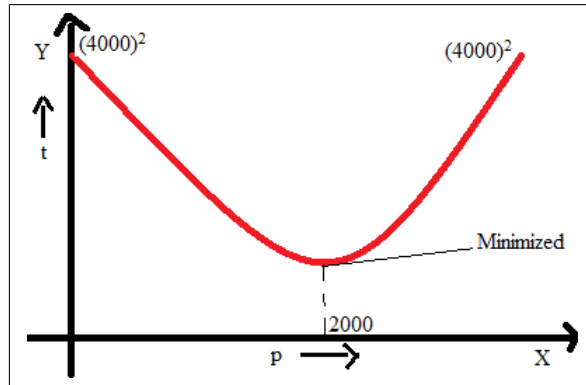


Figure 2: Graph showing that the incentive to deviate minimizes at 2000

NE is equal to welfare maxim choice.

Example 2: Figure: 1 refers to the problem in example 2, where there are have 4000 drivers with the choice of three paths.

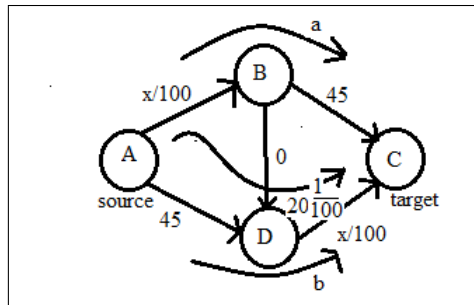


Figure 3: Diagram for the Example 2 showing the NE extra capacity

Ques) Is the NE from the previous example still a NE?

Answer) No, as a driver can do better by switching to $A \rightarrow C \rightarrow D \rightarrow B$ because the travel time on this path is much less than 65.

Ques) What is the NE solution?

Answer) Consider, a and $b > 0$, a solution in which ' a ' drivers take $A \rightarrow C \rightarrow B$, ' b ' drivers take $A \rightarrow D \rightarrow B$ and $4000 - (a + b)$ take the path $A \rightarrow C \rightarrow D \rightarrow B$.

$$\text{travel time on path } A \rightarrow C \rightarrow B : \frac{4000-b}{100} + 45 = 85 - \frac{b}{100}$$

$$\text{similarly, travel time on path } A \rightarrow D \rightarrow B : 85 - \frac{a}{100}$$

$$\text{and travel time on path } A \rightarrow C \rightarrow D \rightarrow B : 80 - \frac{a}{100} - \frac{b}{100}$$

No, solution in which a driver uses $A \rightarrow C \rightarrow B$ or $A \rightarrow D \rightarrow B$ is NE. So, all 4000 drivers will travel on path, $A \rightarrow C \rightarrow D \rightarrow B$. This is the NE solution.

Observations:

1. Braess Paradox: Adding a capacity to the network led to a NE solution in which everyone is worse off.
2. The solution that maximizes social welfare is strictly better than the unique NE.

$$\frac{\text{cost of NE}}{\text{Cost of social welfare maximum solution}} = \text{Price of anarchy}$$

In this example, price of anarchy $\geq \frac{80}{85}$

Results: (Roughgarden and Tardos)

1. For any traffic network $(G = (V, E), s, t)$, this game has a pure strategy NE.
2. For any traffic network $(G = (V, E), s, t)$, price of anarchy ≤ 2 . [More complex algorithm bound it by $\frac{4}{3}$]

For linear delay functions, i.e.,

$$T_e(x) = a_e x + b_e$$

Consider the following “natural ” algorithm:

Start with (p_1, p_2, \dots, p_n) is the choice of an st-path for each of the players $1, 2, \dots, n$.

while (p_1, p_2, \dots, p_n) is not a NE **do**

 Pick a player i who is not playing her best response and replace P_i by a path P_i' with strictly shorter travel time.

end while

Existence of a pure strategy NE: Generally this type of algorithm is known as Tatonnement, and generally they don't converge but for the example 2, this algorithm converges when we find a path optimal for one p .