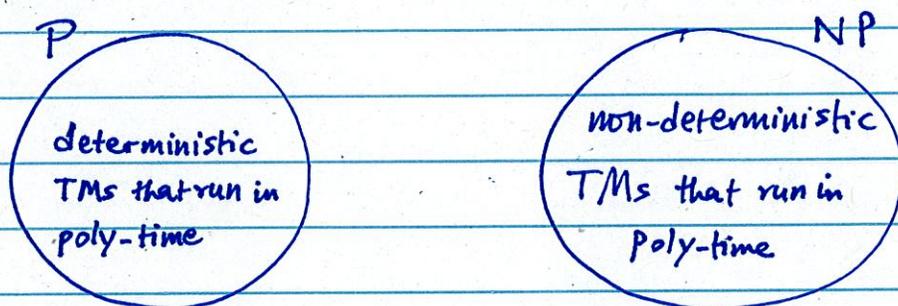


## Diagonalization

Diagonalization was one of the earliest techniques employed (since 1970s) to resolve the  $P \stackrel{?}{=} NP$  question. The general idea is ~~the~~ the following:



We want to ~~show~~ show the existence of a non-det. TM that runs in poly-time & differs from every det. poly-time TM in at least one input-output pair. At first glance, <sup>it seems like</sup> this is something we should be able to achieve using diagonalization.

Despite initial successes, it became clear in '70s that there were some serious obstacles to using diagonalization to resolve  $P \stackrel{?}{=} NP$ .

In this Chapter we'll study some <sup>early</sup> successes obtained by applying diagonalization:

- Time Hierarchy Theorem
- Nondeterministic Time Hierarchy Theorem
- Ladner's Theorem: If  $P \neq NP$ , then there exists a language  $L \in NP \setminus P$  that is not NP-complete.

### (Deterministic Time Hierarchy Theorem)

$$\text{DTIME}(n) \subsetneq \text{DTIME}(n^2).$$

- In other words,  $\text{DTIME}(n)$  is a strict subset of  $\text{DTIME}(n^2)$ .
- In other words, there is a language  $L \in \text{DTIME}(n^2) \setminus \text{DTIME}(n)$ .

### PROOF (by diagonalization):

Consider a Turing machine  $D$  that is deterministic and works as follows:

#### Turing Machine $D$

INPUT:  $x \in \{0, 1\}^*$

#### ALGORITHM

1. ~~Use~~ Use the Universal Turing Machine  $U$  to simulate  $M_x$  (TM encoded by binary string  $x$ ) for  $n = |x|$  steps.
2. If  $U$  halts and outputs  $b \in \{0, 1\}$  then  $D$  outputs  $1-b$ .
3. Otherwise (if  $U$  does not halt within this time) output 0.

Note that the running of  $D$  is  $n^2$  by using the "relaxed" version of the theorem on the existence of a Universal Turing Machine. This is because the theorem

tells us that ~~also~~ there is a Universal Turing Machine  $U$  that ~~can~~ halts in  $T^2$  steps on input  $(\langle M \rangle, x)$  if  $M$  halts on input  $x$  in  $T$  steps. Note that the fact that  $U$  uses a counter to abort if necessary adds very little overhead to the simulation time. (Check this!)

Let  $L$  be the language accepted by  $D$  (i.e.,  $L = \{x \in \{0,1\}^* \mid D(x) = 1\}$ ). Since  $D$  runs in time  $n^2$ ,  $L \in \text{DTIME}(n^2)$ .

We will now show that  $L \notin \text{DTIME}(n)$ . Suppose (for the sake of obtaining a contradiction) that  $L \in \text{DTIME}(n)$ . Then there is a TM  $M$  that runs in time  $n$  such that  $M(x) = D(x) \forall x \in \{0,1\}^*$ .

Now suppose we provide  $\langle M \rangle$  as input to  $D$ . Since  $M$  runs in time  $n$ ,  $M$  will be simulated to completion (on input  $\langle M \rangle$ ) and  $D$  will output a bit that is distinct from what  $M$  would have output. In other words,  $M(\langle M \rangle) \neq D(\langle M \rangle)$  - contradicting our supposition that  $M$  &  $D$  accepted the same language. Thus  $L \notin \text{DTIME}(n)$ .  $\square$

Core of the proof is that we have constructed a machine  $D$  that runs in  $n^2$  time and differs from every machine that runs in  $n$  time on at least one bit.

In fact, if we use the stronger version of the Universal Turing Machine Theorem we get a stronger Time Hierarchy Theorem.

Time Hierarchy Theorem (Hennie & Stearns 1965):

Suppose  $f, g: \mathbb{N} \rightarrow \mathbb{N}$  are ~~functions~~ time constructible functions satisfying  $f(n) \cdot \log(n) = o(g(n))$  then  
$$\text{DTIME}(f(n)) \subsetneq \text{DTIME}(g(n)).$$

(Recall that a time constructible function is a function  $f: \mathbb{N} \rightarrow \mathbb{N}$  that can be computed in  $O(f(n))$  time. Think about where this fact might be needed in the ~~proof~~ proof of the Time Hierarchy Theorem.)

Non-deterministic Time Hierarchy Theorem (Cook, 1972)

If  $f, g$  are time constructible functions satisfying  $f(n+1) = o(g(n))$  then  
$$\text{NTIME}(f(n)) \subsetneq \text{NTIME}(g(n)).$$

First we should ask if the earlier proof we used would work in the non-deterministic setting as well.