

# Analytical Modeling of Parallel Programs

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# Sequential X Parallel

- Evaluation of Sequential Algorithm depends on 'execution time' which depends on the 'input size'
- Evaluation of Parallel Algorithm depends on 'execution time' which depends on (1) input size, and (2) Number of processing elements.

# Total Parallel Overhead

- Parallel Program – Spends extra time in:
  - Interprocess Communication
  - Idling
  - Excess Computation
- What is Idling?  
Elements in parallel system become idle from:
  - Load Imbalance
  - Synchronization
  - Presence of Serial Components

- If all processing elements are not ready for synchronization at the same time, the ones that are ready sooner will be “IDLE” until all the rest are ready.

- What is Excess Computation?

When we compare the difference between the computation performed by the parallel program and the best serial program – it’s the excess computation overhead incurred by parallel program.

# Performance Metrics

To determine the best algorithm, we have to examine the benefits of parallelism. A number of metrics have been used based on desired outcome. These metrics are:

- Execution Time
- Total Parallel Overhead
- Speedup
- Efficiency
- Cost

# Execution Time

- Execution Time:
  - Serial Runtime: Time elapsed between the beginning and the end of its execution on a sequential computer.
  - Parallel Runtime: Time that elapses from the moment a parallel computation starts to the moment the last processing element finishes execution.
- Serial Runtime =  $T_s$
- Parallel Runtime =  $T_p$

# Total Parallel Overhead

- Overhead Function/Total Overhead of a parallel system is the total time collectively spent by all the processing elements over and above that required by the fastest known sequential algorithm.
- $pT_p$  is the total time spent in solving a problem summed over all processing elements.
  - $T_o = pT_p - T_s$



# Speedup (S)

- Speedup is a measure that captures the relative benefit of solving a problem in parallel.
- Speedup = ratio of the serial runtime of the best sequential algorithm for solving a problem to the time taken by the parallel algorithm to solve the same problem on  $p$  processing elements.

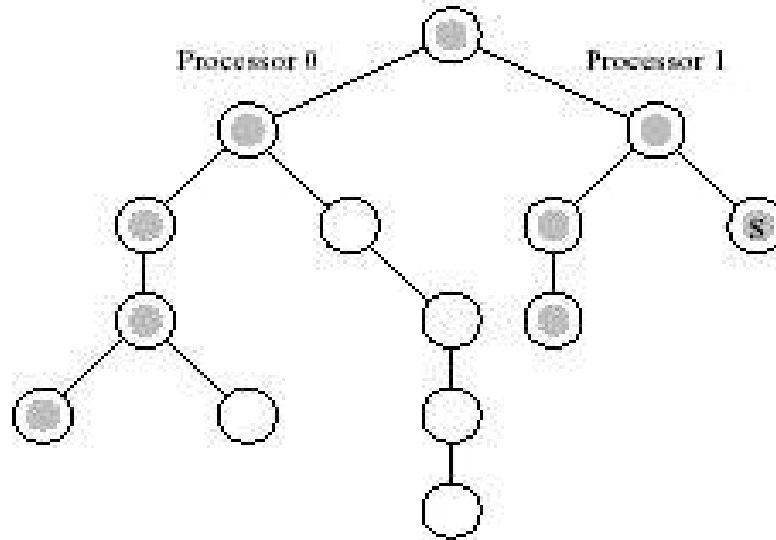


# Note that

- Speedup should not exceed the number of processing elements  $P$ .
- Speedup =  $P$  iff none of the processing elements spends more than  $T_s/P$
- Speedup  $> P \rightarrow$  processing element spends less than time  $T_s/P$  solving the problem. This is called superlinear Speed up.

- Superlinear Speedup occurs if:
  - Work performed by a serial algorithm is greater than its parallel formulation or
  - Hardware features put the serial implementation at a disadvantage.
- Things that affect superlinearity:
  - Increased cache hit ratio resulting from lower problem size per processor -note superlinear speedup
  - Exploratory Decomposition: The Work performed by parallel and serial algorithms is different.

# Superlinear Speedup Example



(It takes one  $t_c$  to visit one node)

Serial Formulation expands the entire tree  $\Rightarrow 14 t_c$

Total Parallel work =  $9 t_c$  (9 node expansions)

Parallel Time =  $5 t_c$

$$\text{Speedup (P = 2)} = 14 t_c / 5 t_c = 2.8 > 2 !$$

# Efficiency

- Definition: Ratio of Speedup to the number of processing elements  $P$ .  $E=S/P$ .
- Efficiency is a measure of the fraction of time for which a processing element is usefully employed. (100% devoted to computation of the algorithm)

# Cost

- Cost is the product of parallel runtime and the number of processing elements used. It reflects the sum of time that each processing element spends solving the problem.
- Cost of solving a problem on a single processing element is the execution time of the fastest known sequential algorithm.
- Cost optimal parallel system has efficiency  $\Theta(1)$

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Cost = work = processor-time-work

# Effect of Granularity on Performance

Assume  $P$  = processing elements and  $n$ =input data.

- To Increase Granularity → we assign larger pieces of  $n$  to each  $P$ .
- Using fewer than the max # of  $P$  to execute a parallel algorithm → scaling down parallel system in terms of  $P$ .
- As the number of  $P$  decreases, the computational time at each processor increases → total parallel runtime increases but  $p \times$  (parallel time) does not increase.
- Therefore if a parallel system with  $n$  processing elements is cost optimal, using  $p$  processing elements ( $p < n$ ) to simulate  $n$  processing elements preserves cost-optimality.